SampleFix: Learning to Correct Programs by Efficient Sampling of Diverse Fixes

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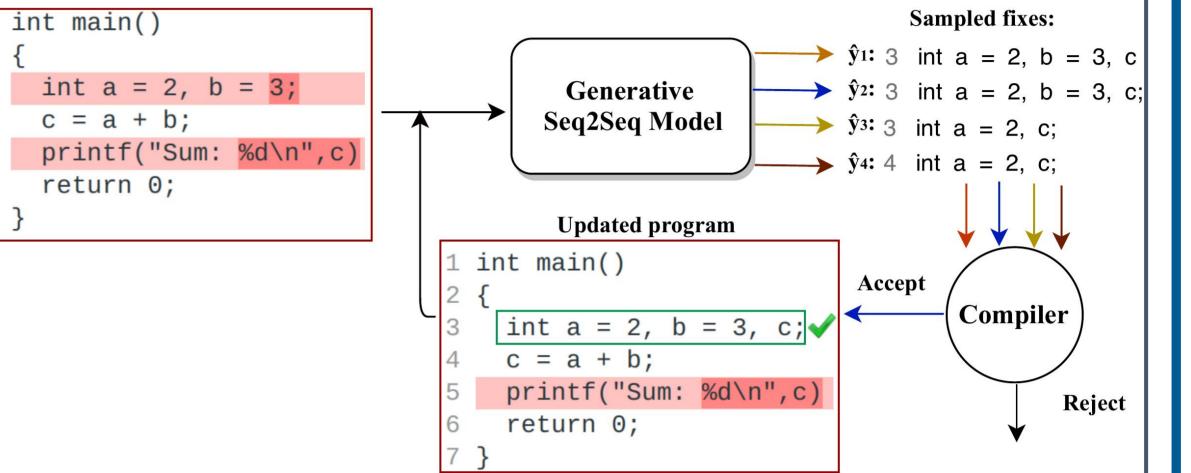
Introduction

- Automatic program correction holds the potential of improving the productivity of programmers.
- A key challenge is ambiguity, as multiple codes can implement the same functionality.
- Therefore, we propose a deep generative model to automatically correct programming errors by learning a distribution over the fixes.

SampleFix: Generative Model for Code Fixes

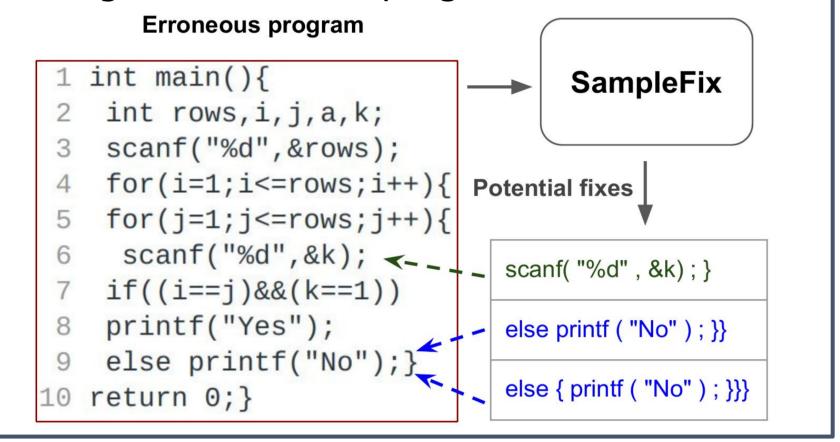
To resolve the programming errors: 1 int

- For a given erroneous program, the generative model draws T fixes.
- To select one out of T fixes, we employ a compiler which evaluates the fixes.
- The compiler selects the **fix** which resolves the largest number of **errors**.



 Our evaluations on common programming errors show the effectiveness of the generation of diverse fixes.

SampleFix captures the inherent ambiguity of the possible fixes by sampling multiple potential fixes for the given erroneous program.



Contribution

- We propose an **efficient generative method** to automatically correct programming errors.
- We propose a novel regularizer to encourage the model to generate **diverse fixes**.
- Our proposed approach shows strong improvement over state-of-the-art methods.

 To resolve the remaining error(s), we iteratively input the updated program to the generative model.

Formulation:

- **Conditional Variational Autoencoders** for generating fixes. $\hat{\mathcal{L}}_{\text{CVAE}} = \frac{1}{T} \sum_{i=1}^{T} \log(p_{\theta}(\mathbf{y}|\hat{\mathbf{z}}_{i}, \mathbf{x})) - D_{\text{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y}) || p(\mathbf{z}|\mathbf{x})) .$
- Enabling diverse samples using the **Best of Many** objective (**BMS**).

 $\hat{\mathcal{L}}_{BMS} = \max_{i} \left(\log(p_{\theta}(\mathbf{y}|\hat{\mathbf{z}}_{i}, \mathbf{x})) \right) - D_{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y}) || p(\mathbf{z}|\mathbf{x}))$

DS-SampleFix: Encouraging diversity with a diversity-sensitive regularizer.

 $\hat{\mathcal{L}}_{\text{DS-BMS}} = \max_{i} \left(\log(p_{\theta}(\mathbf{y}|\hat{\mathbf{z}}_{i}, \mathbf{x})) \right) + \left| \min_{i, j} d(\hat{\mathbf{y}}^{i}, \hat{\mathbf{y}}^{j}) \right| - D_{\text{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y}) || p(\mathbf{z}|\mathbf{x}))$

Encouraging the two closest fixes to have the maximum distance.

Model Architecture and Implementation Details

Model architecture:

In the equations:

- **X** : Erroneous program
- \mathbf{y} : Fix for the program
- **Z** : Latent variable
- T : Number of samples

Beam search decoding:

- We employ the beam search decoding to sample more diverse fixes.
- To sample multiple fixes we decode with beam width of size **K** for each sample **z**.

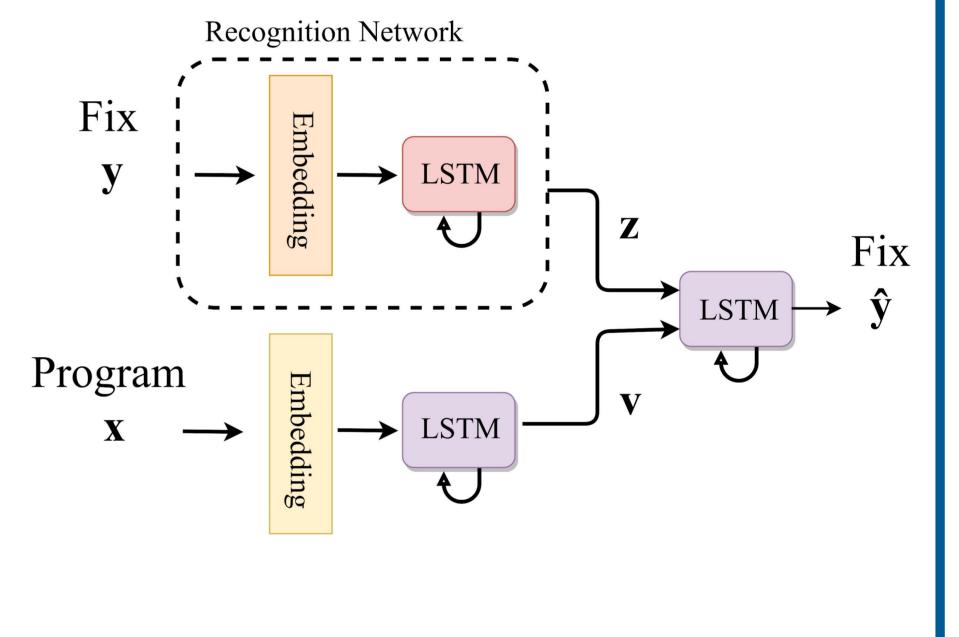
Take-aways:

- **Task:** Automatically correct common programming errors.
- **Insight:** Multiple fixes can implement the same functionality, and there is uncertainty on the intention of the programmer.
- **Our approach:** We propose a generative framework to account for inherent ambiguity and lack of representative datasets
- **Results:** Our approach resolved 65% of error messages.

- Our generative model is based on the sequence-to-sequence architecture, similar to [1].
- All of the networks in our framework consists of 4-layers of LSTM cells with 300 units.
- The recognition network is available to encode the fixes to latent variables **Z** only during training.

Implementation details:

- we train two models, one for repairing the typo errors and another one for miss dec errors.
- We use T = 2 samples to train our models and T = 100 samples during inference time.



Experiments

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3000

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Dataset:

- The **synthetic data** contains the erroneous programs which are synthesized by mutating correct programs written by students.
- The **real-world data** contains 6975 erroneous programs with 16766 error messages written by students.

Results:

 Results of DeepFix, RLAssist, DrRepair, DeepFix + BS(beam search), SampleFix, DS-SampleFix, and DS-SampleFix + BS (beam search).

Effectiveness of Iterative Repair:

- To resolve the multiple errors in a program we use the iterative repair strategy.
- We use up to 5 iterations to resolve multiple error messages.
- We can see that after 5
 iterations, SampleFix, and
 DS-SampleFix resolve more error
 messages than DeepFix.
 11
 12

Qualitative Example:

• Diverse fixes are generated by our DS-SampleFix. The error is highlighted at line 13.

Erroneous Program

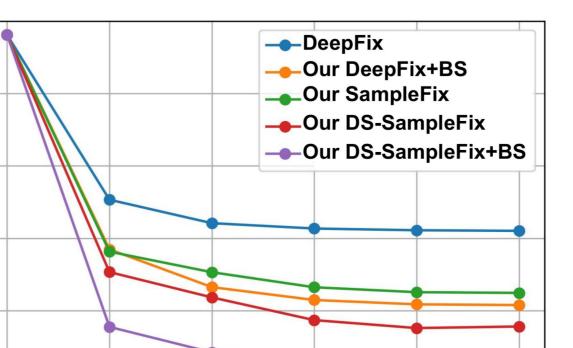
	1 #include <stdio.h></stdio.h>		
to ssages.	2 int main (){ 3 int a , i ; 4 scanf ("%d\n" ,& a);	#	DS-SampleFix Output
sages.	5 int s [a], p [a], g [a]; 6 for ($i = 0$: $i < a$: $i + +$)	1	13 printf ("%d" , g [i]); }

- Typo, Miss Dec, and All refer to typographic, missing variable declarations, and all of the error messages respectively.
- denotes completely fixed programs. denotes resolved error messages.

Models	Туро		Miss Dec		All		Speed (s)
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DeepFix [1]	23.3%	30.8%	10.1%	12.9%	33.4%	40.8%	-
RLAssist [2]	26.6%	39.7%	-	-	-	-	-
DrRepair [3]	-	-	-	-	34.0%	-	-
Our DeepFix+BS	25.8%	38.9%	16.8%	35.3%	39.0%	56.9%	4.82
Our SampleFix	24.8%	38.8%	16.1%	22.8%	40.9%	56.3%	0.88
Our DS-SampleFix	27.7%	40.9%	16.7%	24.7%	44.4%	61.0%	0.88
Our DS-SampleFix + BS	27.8%	45.6%	19.2%	47.9 %	45.2%	65.2%	1.17

References

[1] R. R. Gupta, S. Pal, A. Kanade, and S. K. Shevade. Deepfix: Fixing common c language errors by deep learning. In AAAI, 2017.
 [2] R. Gupta, A. Kanade, and S. Shevade. Deep reinforcement learning for programming language correction. In AAAI, 2019.
 [3] M. Yasunaga and P. Liang. Graph-based, self-supervised program repair from diagnostic feedback. In ICML, 2020.



Iterations

7 scanf ("%d" ,& s [i]);}	2 9 scanf ("%d" ,& p [i]);}}
<pre>8 for (i = 0 ; i < a ; i ++){ 9 scanf ("%d" ,& p [i]);} 10 for (i = 0 ; i < a ; i ++){</pre>	3 14 printf ("end"); }
10 for (i = 0 ; i < a ; i ++){ 11 g [p [i]]= s [i];}	4 13 printf ("%d" , g [i]); }}
<pre>12 for (i = 0 ; i < a ; i ++){ 13 printf ("%d" , g [i]);</pre>	5 11 g [p [i]]= s [i];}}
14 printf ("end"); 15 return 0 ;}	

Key Findings:

- The results show that generating multiple diverse fixes can lead to substantial improvement in the performance of the models.
- In these results, we can see CVAE and beam search decoding are complementary, while CVAE is computationally more efficient in comparison to beam search decoding.
- The performance advantage of **DS-SampleFix**, over **SampleFix** shows the effectiveness of our **novel regularizer**.